

# Testing Self-Timed Circuits with MrGO

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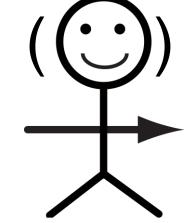
#### MOTIVATION

### Why self-timed?

- Self-timed circuits offer modularity
- Self-timed circuits offer energy efficiency
- Self-timed circuits offer speed

#### What?

- Self-timed networks of state-holding *links* (□□)
- Exchange data at action-capable joints



#### Wanted:

- A general test method to initialize states and control actions for:
  - 1. structural fault testing,
  - 2. at-speed testing, and
  - 3. debug

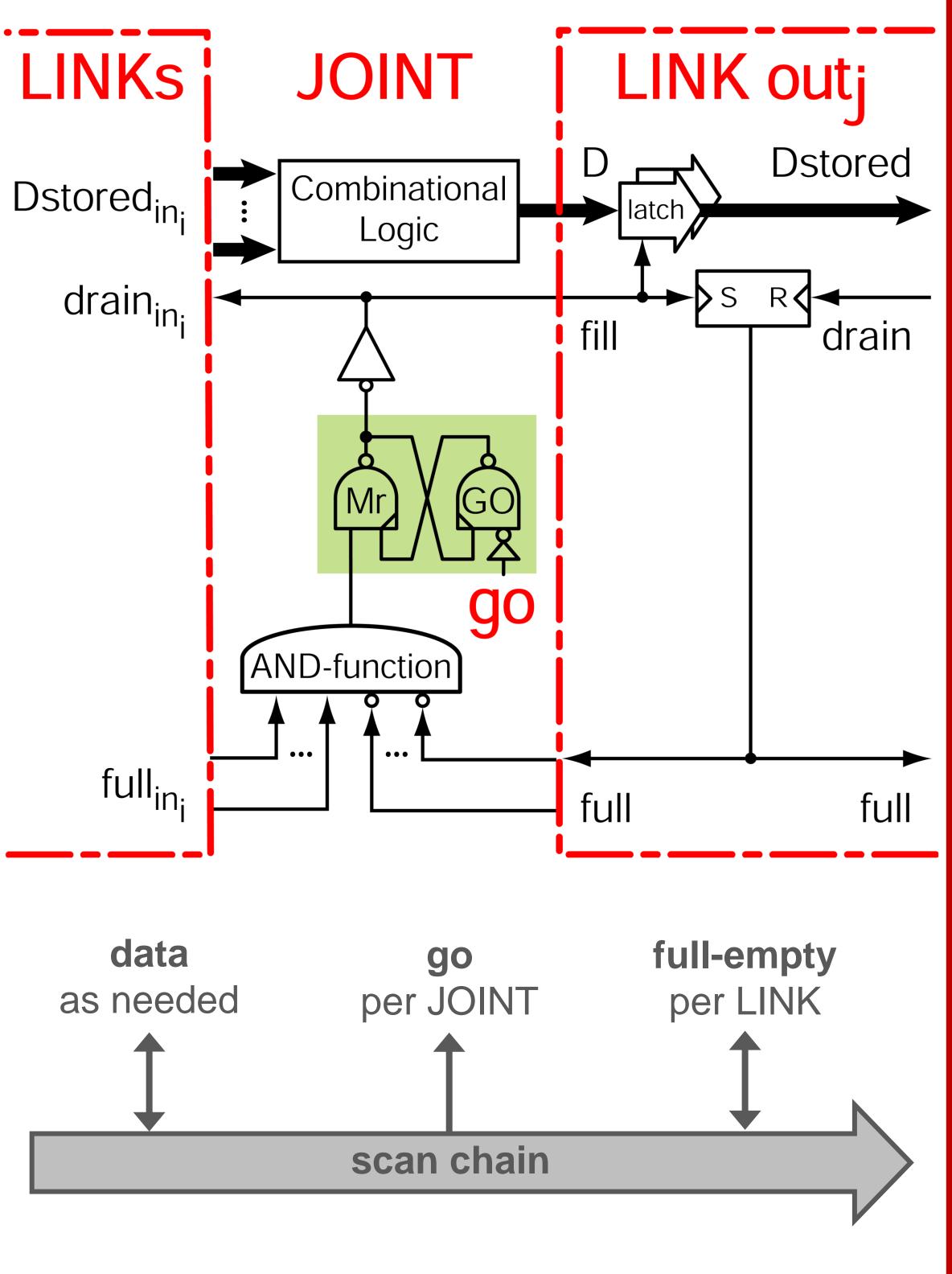
#### SOLUTION

- (Well-known) scan chain to initialize and observe link states
- (New) MrGO to control individual joint actions
  - go is high (GO) run
  - go is low ( ) stop
  - arbiter for safe stop "proper stopper"
  - scan chain delivers go signals

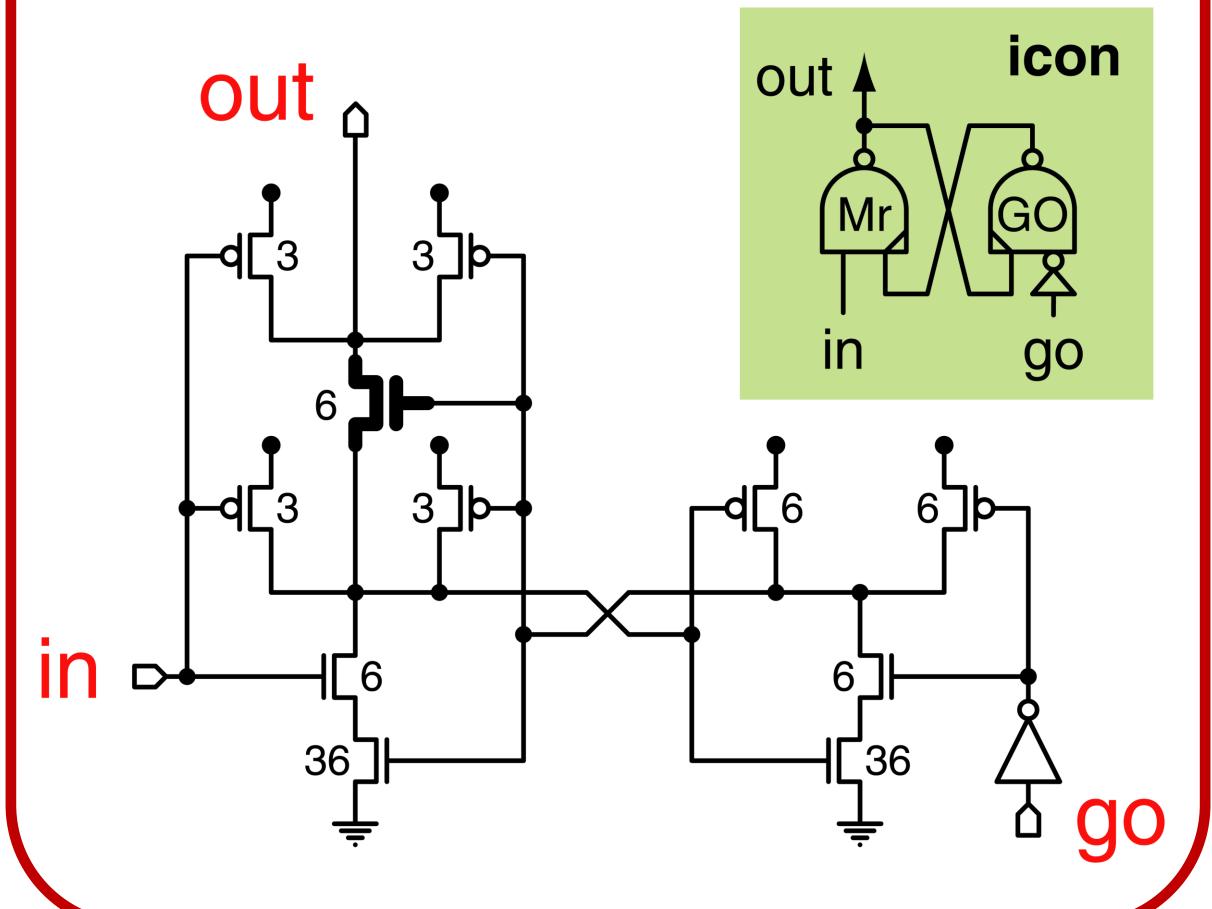
#### REFERENCES

- [1] M. Bushnell and V. Agrawal, "Essentials of Electronic Testing for Digital, Memory, and Mixed-Signal VLSI Circuits," Springer, 2005.
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- [3] M. Roncken, "Defect-Oriented Testability for Asynchronous ICs," *Proceedings of the IEEE*, Vol. 87, No. 2, pp. 363–375, Feb. 1999.
- [4] M. Roncken, S. Mettala Gilla, H. Park, N. Jamadagni, C. Cowan, I. Sutherland, "Naturalized Communication and Testing," *ASYNC 2015.*

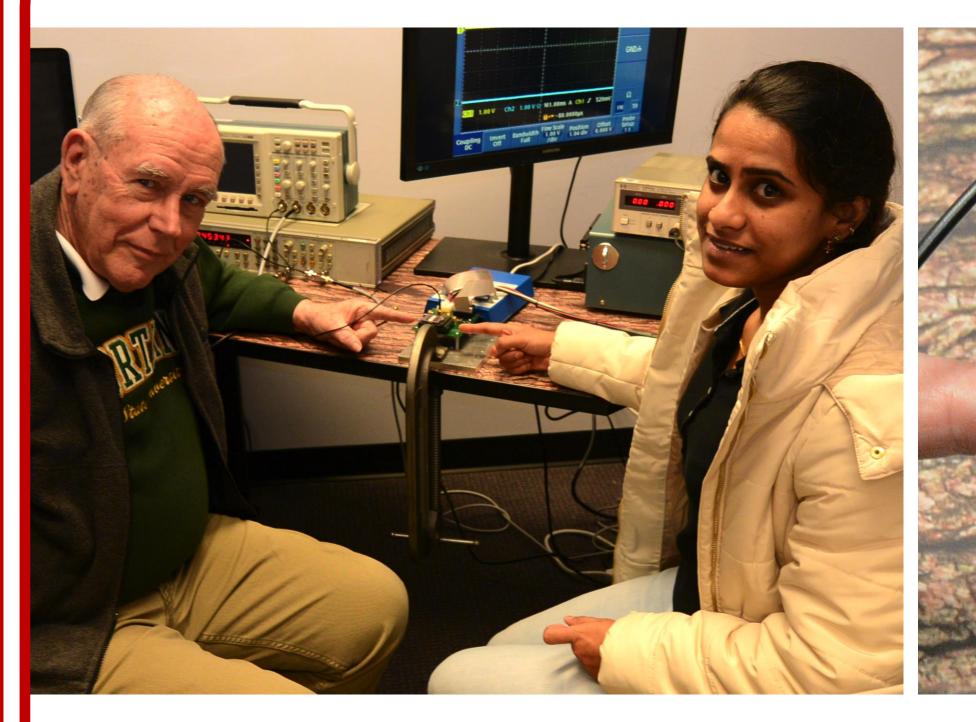
# DESIGN FOR TEST

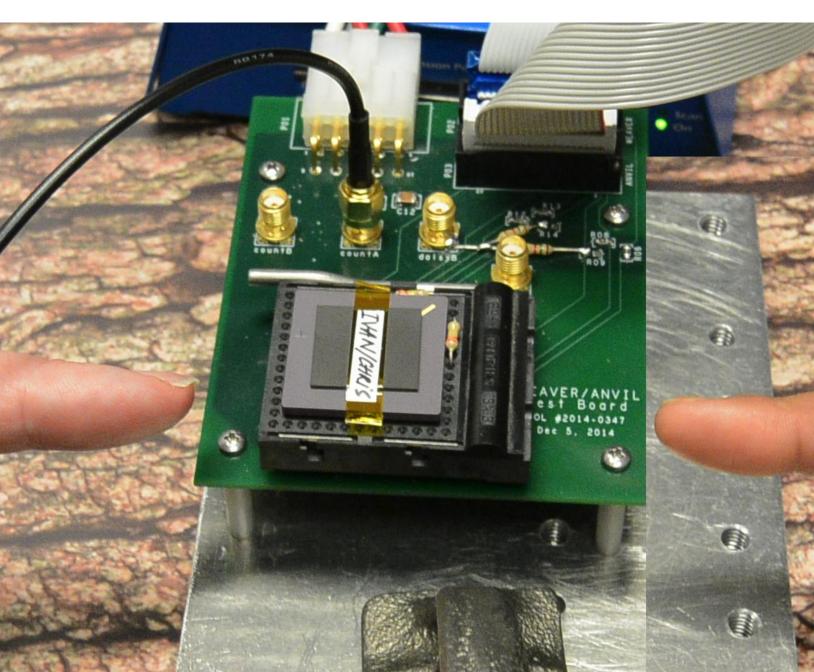


# MrGO circuit

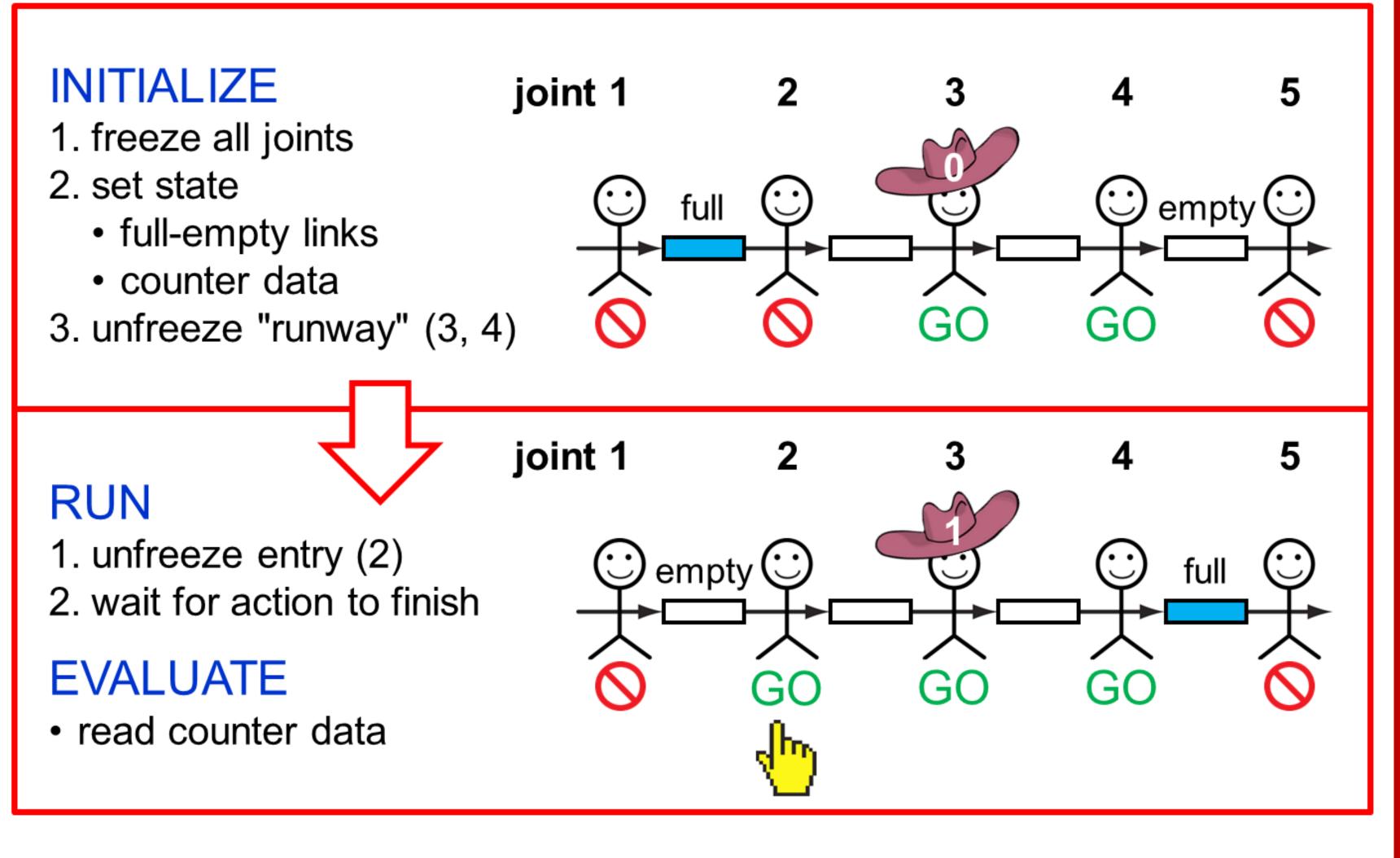


# TEST EXECUTION





# Example: testing a counter at speed



#### Supports:

- 1. Initialization
- 2. Arbitrated stop from full speed
- 3. Single- and multi-step operations
- 4. At-speed testing of sub-systems
- 5. Canopy graph generation
- 6. Testing of structural faults like stuck-at

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